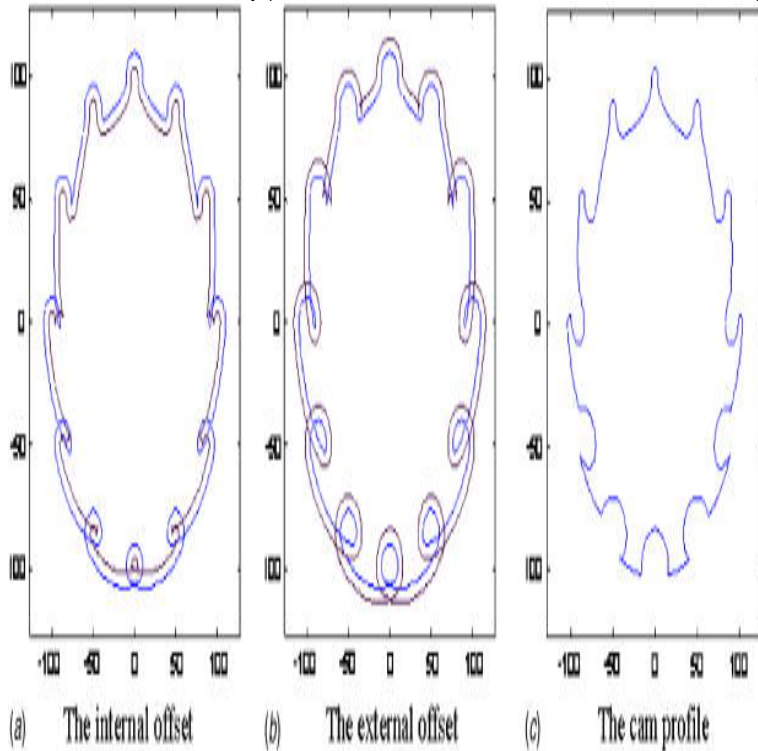


Cams, Gears, Robot And Mechanism Design: Presented At The 1990 ASME Design Technical Conferences, 21



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(JMD) for the (ii) design of direct contact systems, including design of cams, gears, and (vii) design of mechanisms and robotic systems, including design of macro-.The geometric and mechanical design of a thumb mechanism is also presented that allows the reconfiguration of the thumb in the three most favorable poses.

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